

# Probability Background

- Probability spaces
- Random variables
- Expectation
- Basic facts from analysis

• Probability space  $\equiv (\Omega, \mathcal{F}, P)$   
 sample space  $\uparrow$   $\sigma$ -field  $\uparrow$  prob measure  
 (or  $\sigma$ -algebra) (or function)

•  $\Omega \equiv$  set of all possible outcomes of an expt

•  $\mathcal{F} \equiv$  collection of subsets of  $\Omega$  with 3 prop-

i)  $\Omega \in \mathcal{F}$

ii)  $A \in \mathcal{F} \Rightarrow \bar{A} \in \mathcal{F}$

iii)  $A_1, A_2, \dots \in \mathcal{F} \Rightarrow \bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$

• Eg -  $(\Omega, \emptyset)$ ,  $(\Omega, \emptyset, A, \bar{A})$ ,  $2^{\Omega}$  for discrete  $\Omega$

• Prop<sup>n</sup> - For any collection  $\mathcal{C}$  of subsets of  $\Omega$ ,  $\exists$  a **smallest  $\sigma$ -field  $\sigma(\mathcal{C})$**  that contains  $\mathcal{C}$

• Defn - For any metric space  $\Omega$  (eg.  $\mathbb{R}^n$ ), let  $\mathcal{O}$  denote the collection of all open subsets of  $\Omega$ . Then the **Borel  $\sigma$ -field  $\mathcal{B}(\Omega) = \sigma(\mathcal{O})$**

- In particular, for  $\mathbb{R}$ , let  $\mathcal{I} = \{(-\infty, a] \mid a \in \mathbb{R}\}$  be the set of closed intervals. Then

$$\mathcal{B}(\mathbb{R}) = \sigma(\mathcal{I})$$

i.e.,  $\mathcal{B}(\mathbb{R})$  is the smallest  $\sigma$ -field containing all closed intervals (works also for open intervals)

- Note: This is a non-constructive definition. However, one can construct sets which are not in  $\mathcal{B}(\mathbb{R})$ !

(See wikipedia  $\rightarrow$  Vitali set)

- $\mathbb{P} : \mathcal{F} \rightarrow [0, 1]$  is a probability measure

on  $\sigma$ -field  $\mathcal{F}$  if

i)  $\mathbb{P}[\Omega] = 1$

incompatible / disjoint / mutually exclusive

ii)  $\mathbb{P}[A] \in [0, 1] \quad \forall A \in \mathcal{F}$

iii) For  $A_1, A_2, \dots \in \mathcal{F}$  s.t.  $A_i \cap A_j = \emptyset \quad \forall i, j$

$$\mathbb{P}\left[\bigcup_{i=1}^{\infty} A_i\right] = \sum_{i=1}^{\infty} \mathbb{P}[A_i]$$

(KOLMOGOROV'S AXIOMS)

• The above axioms imply the foll<sup>g</sup>

i)  $P[\emptyset] = 0$

ii) If  $A \subseteq B$ , then  $P[A] \leq P[B]$

iii)  $P[\bar{A}] = 1 - P[A]$

iv) For any  $A_1, A_2, \dots \in \mathcal{F}$

(Union bound)

$$P\left[\bigcup_{i=1}^{\infty} A_i\right] \leq \sum_{i=1}^{\infty} P[A_i]$$

v) Given  $A_1, A_2, \dots \in \mathcal{F}$  st  $P[A_i] = 0 \forall i$ ,  
then  $P\left[\bigcup_{i=1}^{\infty} A_i\right] = 0$  (0-measure or negligible sets)

vi) Given  $A_1, A_2, \dots \in \mathcal{F}$  st  $A_i \subseteq A_{i+1} \forall i$   
then  $P\left[\bigcup_{i=1}^{\infty} A_i\right] = \lim_{i \rightarrow \infty} P[A_i]$

(Sequential continuity)

Try proving these/read up

• Random variable  $\equiv$  'measurable' fn on  $\Omega$

• A fn  $f: (\Omega, \mathcal{F}) \rightarrow (\mathbb{R}, \mathcal{B})$  is **measurable** if  $\forall A \in \mathcal{B}$ , we have  $f^{-1}(A) \in \mathcal{F}$

• (In this course, we will mostly ignore measurability - however in more complex settings, one needs to be careful...)

• Defn - A random variable  $X$  on a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  is a measurable fn  $X: \Omega \rightarrow \mathbb{R}$

# Almost sure

- We are interested in all events which are non-negligible (i.e., all  $A$  s.t.  $\mathbb{P}[A] > 0$ ).

Defn - For given  $(\Omega, \mathcal{F}, \mathbb{P})$ , a property  $P$  holds almost surely if  $\mathbb{P}[\{\omega \mid \omega \text{ satisfies } P\}] = 1$

- Similarly for r.v.s  $X, Y$ , we say  $X = Y$  almost surely (or  $X = Y$  a.s.) if

$$\mathbb{P}[\{\omega \mid X(\omega) \neq Y(\omega)\}] = 0$$

• The signature feature of a random variable  $X$  is its cumulative distribution fn  $F: \mathbb{R} \rightarrow [0,1]$ ,  $F(t) = \mathbb{P}[X \leq t]$

- recall the Borel  $\sigma$ -field  $\mathcal{B}(\mathbb{R})$  was constructed using only (closed) intervals  $(-\infty, t]$

- the  $\leq$  is a convention; we could have as well defined it as  $\mathbb{P}[X < t]$ .

This would correspond to constructing  $\mathcal{B}(\mathbb{R})$  using open intervals...

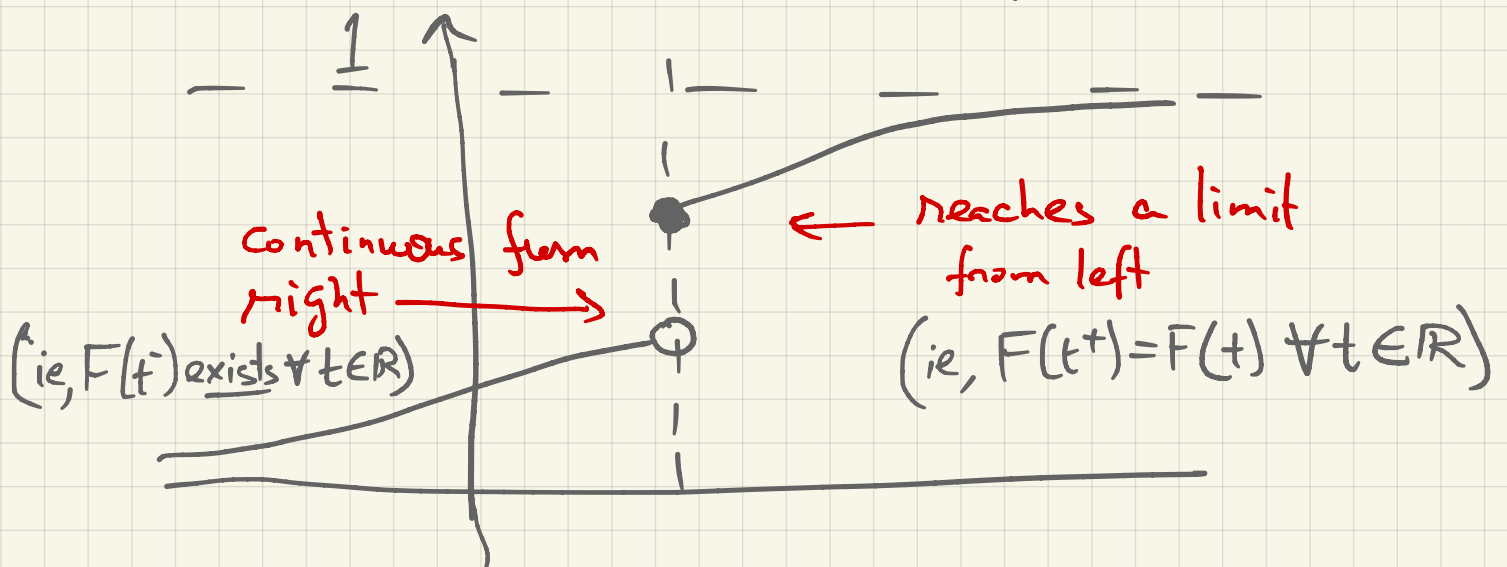
- CDFs are awesome! All random variables have one.

# Properties of CDFs

- $\lim_{t \rightarrow -\infty} F(t) = 0, \quad \lim_{t \rightarrow \infty} F(t) = 1$

- $F$  is **non-decreasing**

- $F$  is **RCLL** (Right continuous, Left limits)



This is a consequence of  $\leq$  convention

- Every non-decreasing, RCLL fn from 0 to 1 is a CDF for some  $X \dots$



- Random variables can be discrete or continuous

| <u>Discrete</u>   | <u>(Absolutely) Continuous</u>   |
|---|--|
| <ul style="list-style-type: none"> <li>- <math>\exists x_1, x_2, \dots \in \mathbb{R}</math> s.t.</li> <li>- <math>\sum_{i=1}^{\infty} \mathbb{P}[X=x_i] = 1</math></li> <li>- <math>p(x_i) = \mathbb{P}[X=x_i]</math><br/>probability mass fn (pmf)</li> <li>- <math>F(t) = \sum_{x_i \leq t} p(x_i)</math></li> </ul> | <ul style="list-style-type: none"> <li>- <math>\exists</math> fn <math>f: \mathbb{R} \rightarrow \mathbb{R}^+</math> s.t.</li> <li>- <math>F(t) = \int_{-\infty}^t f(x) dx</math><br/>probability density fn (pdf)</li> <li>- <math>\mathbb{P}[X=x] = 0 \quad \forall x \in \mathbb{R}</math></li> </ul> |

- See Ch 2.1 of Brémaud (DiscProb) for examples of distributions

Discrete: Bernoulli( $p$ ), Binomial( $n, p$ ),  
Geometric( $p$ ), Poisson( $\lambda$ )  
Multinomial( $m, p_1, p_2, \dots, p_n$ ) =  $\binom{m \text{ balls in}}{n \text{ bins}}$

Continuous: Uniform( $a, b$ ), Gaussian  $N(\mu, \sigma^2)$   
Exponential( $\lambda$ )

(for the last two, see Brémaud - Markov Chains)

- **Random Vectors**  $\equiv$  Collection of random variables  $(X_i)_{i \in I}$  on prob space  $(\Omega, \mathcal{F}, \mathbb{P})$

- Joint distribution fn  $F: \mathbb{R}^n \rightarrow [0, 1]$   
$$F(t_1, t_2, \dots, t_n) = \mathbb{P}[X_1 \leq t_1 \cap X_2 \leq t_2 \cap \dots \cap X_n \leq t_n]$$
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- **Independence** - 2 events  $A, B \in \mathcal{F}$  are indep if  $\mathbb{P}[A \cap B] = \mathbb{P}[A] \mathbb{P}[B]$ 
  - Different from mutually exclusive/disjoint

- For events  $A_1, A_2, \dots, A_n$ 
  - $\mathbb{P}[A_i \cap A_j] = \mathbb{P}[A_i] \mathbb{P}[A_j] \forall i, j$   
 $\Rightarrow A_i$ 's are **pairwise independent**
  - $\mathbb{P}[\bigcap_{i=1}^n A_i] = \prod_{i=1}^n \mathbb{P}[A_i]$   
 $\Rightarrow A_i$ 's are **mutually independent**

• 2 random variables  $X, Y$  are independent if  $\forall x, y \in \Omega$

$$\mathbb{P}[X=x, Y=y] = \mathbb{P}[X=x] \mathbb{P}[Y=y]$$

• r.v.s  $X, Y$  are said to be conditionally independent given  $Z$  if  $\forall x, y, z$ , we have

$$\mathbb{P}[X=x, Y=y | Z=z] = \mathbb{P}[X=x | Z=z] \mathbb{P}[Y=y | Z=z]$$

(see Bérémoud for conditional probability)

• Notation -  $X, Y$  independent is written as  $X \perp\!\!\!\perp Y$

# Expectation

- We will focus first on discrete r.v.

Defn - For r.v.  $X$  taking values in countable set  $E$ , and function  $g: E \rightarrow \mathbb{R}$  st either  $g$  is non-negative or  $\sum_{x \in E} |g(x)| p(x) < \infty$ ,  
then  $E[g(X)] = \sum_{x \in E} \underbrace{p(x)}_{\text{pmf}} \underbrace{g(x)}_{\mathbb{P}[X=x]}$  ↖ 'integrable'

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## An important example

• For any  $A \in \mathcal{F}$ ,  $E[\mathbb{1}_A] = P[A]$   
where  $\mathbb{1}_A \equiv$  indicator r.v.  $\left( \mathbb{1}_A = \begin{cases} 1 & \text{if } A \text{ true} \\ 0 & \text{otherwise} \end{cases} \right)$

• Indicator r.v. are very useful for computations!!

For continuous distributions

- Suppose  $X$  has pdf  $f$  (ie, absolute continuous)

$$\text{then } E[g(X)] = \int_{-\infty}^{\infty} g(x) f(x) dx$$

for any  $g$  s.t.  $\int_{-\infty}^{\infty} |g(x)| f(x) dx < \infty$

- More generally,  $X$  could be discrete + continuous

- FACT - Any CDF  $F$  has only a countable number of jumps

- Let  $\{d_n\}_{n \geq 1}$  be the discontinuity points for a given CDF  $F$

$$F_d(t) \triangleq \sum_{d_n \leq t} (F(d_n) - F(d_n^-)), \quad F_c(t) = F(t) - F_d(t)$$

'jumps'                      'continuous part'

$$\text{then } \mathbb{E}[g(x)] = \int_{-\infty}^{\infty} g(x) dF(x)$$

↳ The Lebesgue integral of  $g$  w.r.t measure  $F$ ,

$$= \sum_{n=1}^{\infty} g(d_n) (F(d_n) - F(d_n^-)) + \int_{-\infty}^{\infty} g(x) f_c(x) dx$$

where  $f_c(x)$  is a function such

$$\text{that } F_c(t) = \int_{-\infty}^t f_c(x) dx$$

$$\left( \text{i.e., } f_c(x) = \frac{d}{dx} F_c(x) \right)$$

# Properties of $E[X]$

i) Linearity of Expectation

$$E[\lambda_1 g_1(x) + \lambda_2 g_2(x)] = \lambda_1 E[g_1(x)] + \lambda_2 E[g_2(x)]$$

for any  $\lambda_1, \lambda_2 \in \mathbb{R}$ ,  $g_1, g_2$  integrable

ii) For  $g_1, g_2$  s.t.  $g_1(x) \leq g_2(x) \forall x \in \mathbb{R}$

$$\Rightarrow E[g_1(x)] \leq E[g_2(x)] \quad (\text{monotonicity})$$

iii) If  $X \perp Y \Rightarrow E[g(x)h(y)] = E[g(x)]E[h(y)]$

iv) For  $X \geq 0$  (ie,  $P[X < 0] = 0$ )

$$E[X] = \int_0^{\infty} (1 - F(t)) dt$$

In particular, if  $X \in \mathbb{N}$ , then

$$E[X] = \sum_{n=1}^{\infty} P[X \geq n]$$

# Mean, variance, moments

• Mean  $\mu = \mathbb{E}[X]$

Variance  $\sigma^2 = \mathbb{E}[(X-\mu)^2]$   
 $= \mathbb{E}[X^2] - (\mathbb{E}[X])^2$

• Raw moments -  $m_k = \mathbb{E}[X^k]$

Centered moments -  $\sigma_k = \mathbb{E}[(X-\mu)^k]$

• If  $X_1 \perp X_2$ ,  $Y = X_1 + X_2$

then  $\sigma_k(Y) = \sigma_k(X_1) + \sigma_k(X_2)$

(However, for mean, this is always true thanks to linearity!)



## Some useful facts about integration

- An important part of analysis / measure theory is to formalize the notion of the integral. For our class, we will just need some important results that come out of this formalism
- Consider a sequence of random variables  $X_1, X_2, \dots$

i) If  $X_n(\omega) \geq 0$  a.s. and  $X_n(\omega) \leq X_{n+1}(\omega)$  a.s. for all  $n$ , then

$$\lim_{n \rightarrow \infty} E[X_n] = E\left[\lim_{n \rightarrow \infty} X_n\right]$$

(monotone convergence)

ii) If  $|X_n(\omega)| \leq Y(\omega)$  a.s. for all  $n$ ,

and  $E[|Y|] < \infty$ , then

$$\lim_{n \rightarrow \infty} E[X_n] = E\left[\lim_{n \rightarrow \infty} X_n\right]$$

(dominated  
convergence)

iii) If  $|X_n(\omega)| \leq C$  a.s. for all  $n$ , then

$$\lim_{n \rightarrow \infty} E[X_n] = E\left[\lim_{n \rightarrow \infty} X_n\right]$$

(bounded  
convergence)

iv) If  $X_n \geq Y$  a.s. for all  $n$ , and

$E[|Y|] < \infty$ , then

$$E\left[\liminf_{n \rightarrow \infty} X_n\right] \leq \liminf_{n \rightarrow \infty} E[X_n]$$

(Fatou's Lemma)

All the above hold for discrete  
no (and series) as well - see  
chapter 4.1.3 of Breiman DP.  
(Also see Appendix A1 for proofs)

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• Interchanging sums and integrals

• If  $X_n \geq 0$  then  $E\left[\sum_{n=1}^{\infty} X_n\right] = \sum_{n=1}^{\infty} E[X_n]$

If  $X(t) \geq 0$  then  $E\left[\int_{-\infty}^{\infty} X(t) dt\right] = \int_{-\infty}^{\infty} E[X(t)] dt$

(Tonelli's Theorem)

• If  $E\left[\sum_{n=1}^{\infty} |X_n|\right] < \infty$ , then  $E\left[\sum X_n\right] = \sum E[X_n]$

If  $E\left[\int_{-\infty}^{\infty} |X(t)| dt\right] < \infty$ , then  $E\left[\int X(t) dt\right] = \int E[X(t)] dt$

(Fubini's Theorem)