

Multi fare-class capacity allocation (contnd.)

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- Problem - Capacity c , fare classes $P_1 \leq P_2 \leq \dots \leq P_n$
(D_1, F_1) (D_2, F_2) (D_n, F_n)
- Bellman Eqn - If control \equiv # of seats allocated

$$V_j(s) = \max_{y \in \{0, 1, \dots, s\}} \mathbb{E}_{F_j} \left[P_j \min(D_j, y) + V_{j+1}(\max(s-y, s-D_j)) \right]$$

2 approaches to solving -

1) When D_j, y are continuous

- Assume D_j available before taking action

$$\bar{V}_j(s) = \mathbb{E}_{F_j} \left[\max_{y \in \underbrace{\{(s-D_j)^+, \dots, s\}}_{\text{random set } Y(s, D_j)}} \{ P_j (s-y) + \bar{V}_{j+1}(y) \} \right]$$

- Show that $\bar{V}_j(s)$ is concave in y (TODO)

- Consequently, $y^*(s) = \begin{cases} s - \min\{x_j^*, D_j\} & ; s \geq x_j^* \\ s & ; s < x_j^* \end{cases}$

where $x_j^* = \arg \max_x \bar{V}_{j+1}(x)$

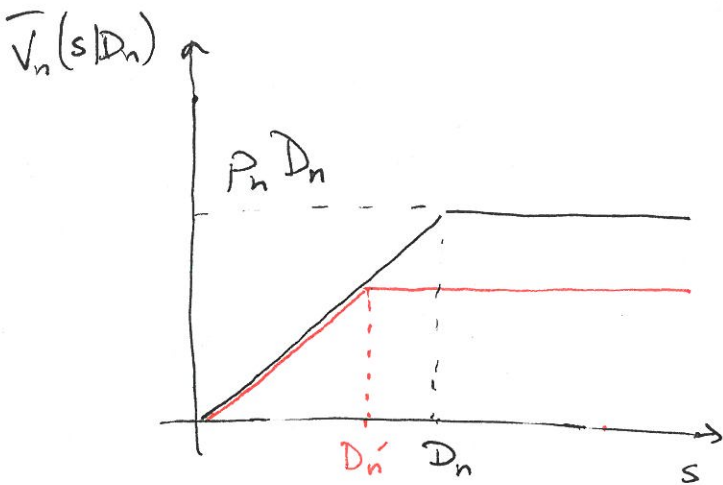
2) We study monotonicity properties of $\bar{V}_j(s)$ w.r.t s and j (for discrete capacity allocations)

Concavity of $\bar{V}_j(\cdot)$

(2)

- Induction on $j \in \{n, n-1, \dots, 1\}$

- $\bar{V}_n(s|D_n) \triangleq \max_{(s-D_n)^+ \leq y \leq s} \underbrace{[-P_n(s-D_n)^+ + P_n s]}_{\text{alt form for } P_n \min\{s, D_n\}}$



- Random fn (depends on D_n)
- Concave in $s \forall D_n \in \mathbb{R}^+$
- $\bar{V}_n(s) = \mathbb{E}[\bar{V}_n(s|D_n)]$
 \Rightarrow linear combination of concave fns
 \Rightarrow concave in s

- Assume $\bar{V}_{j+1}(s)$ is concave in s ,

• Let $H_j(y) = [-P_j y + \bar{V}_{j+1}(y)]$ (concave in s)

$V_j(s|D_j) = \max_{(s-D_j)^+ \leq y \leq s} [H_j(y)] + P_j s$

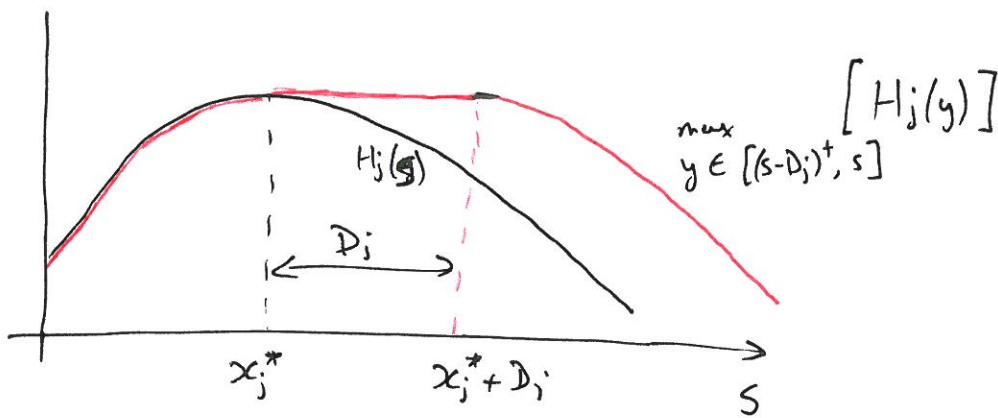
If $\max_{(s-D_j)^+ \leq y \leq s} [H_j(y)]$ concave $\Rightarrow V_j(s) = \mathbb{E}[V_j(s|D_j)]$ is concave

• Define $x_j^* = \text{argmax}_{y \in [0, \infty)} [H_j(y)]$

Note - $x_{n-1}^* = F_n^{-1}(1 - \frac{P_{n-1}}{P_n})$ (same as 2-class ~~node~~ setting)

Now from previous discussion re maximizing ⁽³⁾
 a concave fn over a random interval, we have

$$y_j^* = \arg \max_{y \in [(s-D_j)^+, s]} [H_j(y)] = \begin{cases} s & ; s \leq x_j^* \\ x_j^* & ; s-D_j \leq x_j^* \leq s \\ s-D_j & ; s-D_j \geq x_j^* \end{cases}$$



Thus
 $\max_{y \in [(s-D_j)^+, s]} \{H_j(y)\}$
 is concave in s
 $\forall D_j$

- Note - the above argument also works if D_j is discrete

Moreover, we can modify it to show

$$\Delta \bar{V}_j(s) = \bar{V}_j(s+1) - \bar{V}_j(s) \leq \Delta \bar{V}_j(s-1) \quad \forall s$$

(This is an intuitive 'diminishing returns' property of increasing capacity)

Alternate characterization of protection levels

(4)

- Idea - Show protection levels are monotone
 - Use it to get interpretable characterization of protection levels (including for discrete protection levels)

Claim \otimes : $\bar{V}_j(s+1) - \bar{V}_j(s) \geq \bar{V}_{j+1}(s+1) - \bar{V}_{j+1}(s) \quad \forall j, \forall s$

- Intuitive 'increasing returns' property - More capacity later has higher returns

- Implication - Monotonicity of x_j^*

Recall $x_j^* = \operatorname{argmax}_{y \in [0, \infty)} [-P_j y + \bar{V}_{j+1}(y)]$

Alt: x_j^* is first y s.t. $\bar{V}_j(y+1) - \bar{V}_j(y) < 0$
 $\triangleq \Delta \bar{V}_j(y)$

$$\Rightarrow -P_j + \bar{V}_j(x_j^* + 1) - \bar{V}_j(x_j^*) < 0$$

$$\Rightarrow -P_{j+1} + \bar{V}_{j+1}(x_j^* + 1) - \bar{V}_{j+1}(x_j^*) < 0 \quad \left(\begin{array}{l} \text{from } \otimes \text{ and} \\ P_{j+1} \geq P_j \end{array} \right)$$

$$\Rightarrow \boxed{x_{j+1}^* \leq x_j^*} \quad \left(\begin{array}{l} \text{Since } x_{j+1}^* \text{ is smallest } y \text{ where} \\ \Delta \bar{V}_{j+1}(y) < 0 \end{array} \right)$$

$$\Rightarrow x_1^* \geq x_2^* \geq \dots \geq x_n^* = 0 \quad - \text{ NESTED Protection levels}$$

Combining claim $\textcircled{*}$ with our previous 'diminishing returns of capacity' result, we get. ⑤

Thm - $\forall j \in \{1, 2, \dots, n-1\}, s \in \{0, 1, \dots, c\}$

$$i) \quad \Delta \bar{V}_j(s+1) \leq \Delta \bar{V}_j(s)$$

$$ii) \quad \Delta \bar{V}_j(s) \geq \Delta \bar{V}_{j+1}(s)$$

Pf - We have already argued (i). For (ii), we consider

2 cases

Case 1 - $s+1 \leq x_j^*$ ($\Rightarrow s \leq x_j^*$, i.e., capacity below x_j^*)

$$\Rightarrow \bar{V}_j(s | D_j) = V_{j+1}(s), \quad \bar{V}_j(s+1 | D_j) = V_{j+1}(s+1) \quad \forall D_j$$

$$\Rightarrow \Delta V_j(s) = \Delta \bar{V}_{j+1}(s)$$

Case 2 - $s \geq x_j^*$ ($\Rightarrow s+1 \geq x_j^*$; We accept $\min\{s-x_j^*, D_j\}$)

$$\begin{aligned} \Rightarrow \Delta \bar{V}_j(s | D_j) &= P_j \left[\min(s-x_j^*+1, D_j) - \min(s-x_j^*, D_j) \right] + \\ &\quad V_{j+1}(\max(x_j^*, s+1-D_j)) - V_{j+1}(\max(x_j^*, s-D_j)) \end{aligned}$$

$$= P_j \cdot \mathbb{1}_{\{D_j \geq s+1-x_j^*\}} + \mathbb{1}_{\{D_j \leq s-x_j^*\}} \left[V_{j+1}(s+1-D_j) - V_{j+1}(s-D_j) \right]$$

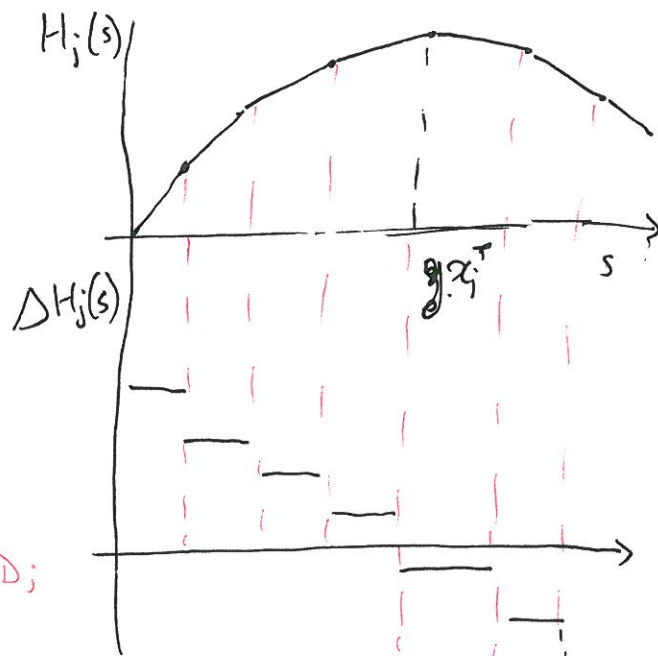
$$= P_j + \mathbb{1}_{\{D_j \leq s-x_j^*\}} \left[\Delta H_j(s-D_j) \right]$$

• Now from before, we know $H_j(s)$ is (6)
 concave (and thus $\Delta H_j(s - D_j)$ is decreasing)

Moreover, $x_j^* \equiv \min_{y \in [0, \infty]} \{ \Delta H_j(y) < 0 \}$

$$\Rightarrow \mathbb{1}_{\{s \geq x_j^* + D_j\}} \Delta H_j(s - D_j) \leq 0 \quad \forall D_j$$

and also decreasing in s



$$\Rightarrow \mathbb{1}_{\{s \geq x_j^* + D_j\}} \Delta H_j(s - D_j) \geq \mathbb{1}_{\{s \geq x_j^*\}} \Delta H_j(s)$$

← increasing $s \rightarrow s + D_j$

$$= \mathbb{1}_{\{s \geq x_j^*\}} \left(-P_j + V_{j+1}(s+1) - V_{j+1}(s) \right)$$

This is true under our assumption

$$\Rightarrow \Delta \bar{V}_j(s | D_j) \geq V_{j+1}(s+1) - V_{j+1}(s) = \Delta V_{j+1}(s)$$

$$\Rightarrow \Delta V_j(s) \geq \Delta V_{j+1}(s) \quad \square$$