

Last class

- Gaussian-Gaussian model (known Σ , unknown μ)
- Gaussian-Gamma model (unknown Σ , known μ)
- Gaussian-Gamma-Gaussian (?) model



ORIE 4742 - Info Theory and Bayesian ML

Chapter 8: Bayesian Regression

simplest "general" model for continuous data

- basis functions (for today - fixed basis)
- next class - infinite families of basis fns

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(eg- polynomial regression, but with no max degree)

'need some form of implicit regularization'

idea - Gaussian process

- Bayesian model selection

normal-normal model for unknown μ

- data $D = \{X_1, X_2, \dots, X_n\} \in \mathbb{R}^n$
- model \mathcal{M} : X_i i.i.d. from $\mathcal{N}(\mu, \tau)$, with **unknown μ** , **known $\tau = 1/\sigma^2$** Precision

normal-normal model

- likelihood: $p(D|\mu) \propto \exp(-\tau \sum_{i=1}^n (x_i - \mu)^2 / 2)$
- prior: $\mu \sim \mathcal{N}(m_\mu, 1/\tau_\mu) \propto \exp(-\tau_\mu (\mu - m_\mu)^2 / 2)$ $\tau_\mu, m_\mu \equiv$ prior hyperparameters
- posterior: let $\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$, $m_D = \frac{n\tau \cdot \bar{x} + \tau_\mu \cdot m_\mu}{n\tau + \tau_\mu}$ and $\tau_D = \frac{n\tau + \tau_\mu}{}$ shrinkage estimator 'precisions add'

MLE

$$p(\mu|D) \sim \mathcal{N}(m_D, 1/\tau_D)$$

$$\mu = m_D + \frac{1}{\sqrt{\tau_D}} Z_1$$

- posterior predictive distribution: $Z_1, Z_2 \sim \mathcal{N}(0, 1)$

$$p(x|D) \sim \mathcal{N}(m_D, 1/\tau + 1/\tau_D)$$

$$X = \mu + \frac{1}{\sqrt{\tau}} Z_2$$

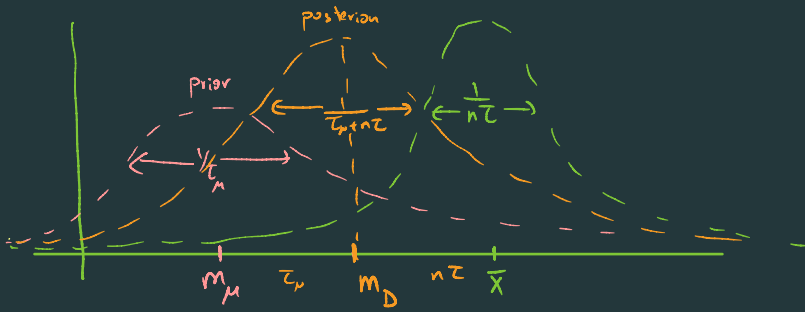
aside

$$X \sim \mathcal{N}(\mu, \sigma^2)$$

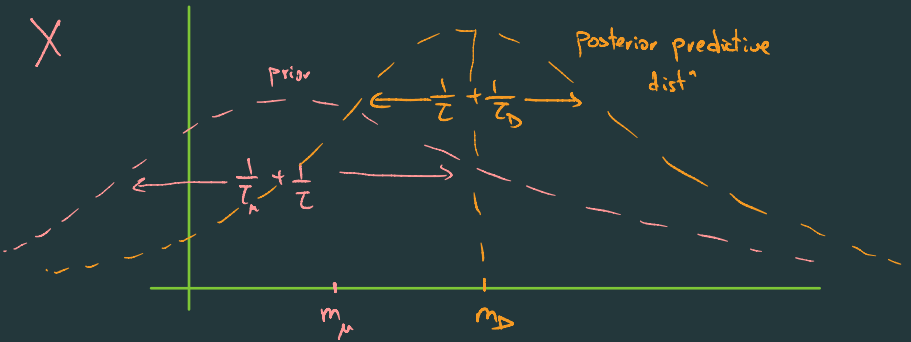
$$\Rightarrow X = \mu + \sigma Z$$

$$Z \sim \mathcal{N}(0, 1)$$

μ



X



what is linear regression?

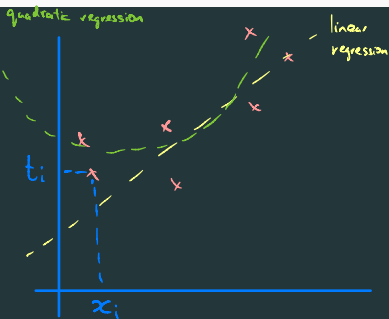
Data - $(x_1, t_1), (x_2, t_2), \dots, (x_n, t_n)$
 ↑ ↑
 observation target

Model - $y(x) = \sum_{j=1}^M w_j \phi_j(x)$
 ↑ ↑
 weights basis fns

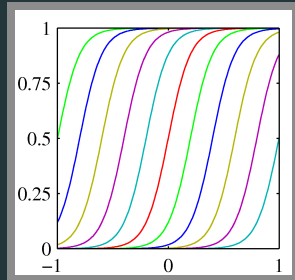
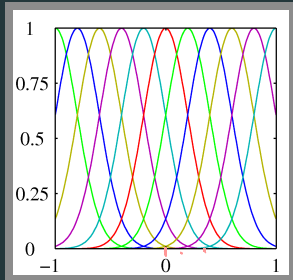
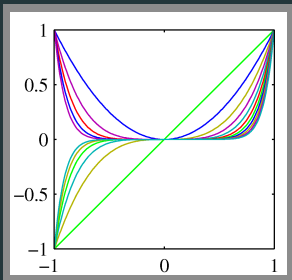
$t(x) = y(x) + \epsilon$ ← iid noise $\epsilon \sim N(0, 1/\beta)$
 ↑ ↑
 assume $\phi_1(x)=1$ noise precision

Ex - linear regression - $t(x) = w_1 + w_2 x + \epsilon$

(degree 3) polynomial regression - $t(x) = w_1 + w_2 x + w_3 x^2 + w_4 x^3 + \epsilon$
 $\phi = (1, x, x^2, x^3)$



basis functions (from Bishop Ch 6)



polynomial basis

$$1, x, x^2, x^3, x^4, \dots$$

$$\phi_j(x) = x^{j-1} \text{ (Taylor series)}$$

• $\phi_j(x) = \sin(\omega_j x + \mu_j)$ - Fourier basis (Fourier series)

• Wavelet basis



Gaussian basis fn

$$\phi_j(x) = e^{-\frac{(x-\mu_j)^2}{s_j}}$$

μ_j ← location
 s_j ← scale

Sigmoidal basis fn

$$\phi_j(x) = \frac{1}{1 + e^{-\frac{(x-\mu_j)}{s_j}}}$$

regression: the frequentist view

$$\cdot t_i = \sum_{j=1}^M w_j \phi_j(x_i) + \varepsilon_i, \quad \varepsilon_i \sim N(0, \sigma^2), \text{ iid}$$

$$\cdot \text{Design matrix } \Phi = \begin{pmatrix} \phi_1(x_1) & \phi_2(x_1) & \dots & \phi_M(x_1) \\ \phi_1(x_2) & \phi_2(x_2) & \dots & \phi_M(x_2) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_1(x_n) & \phi_2(x_n) & \dots & \phi_M(x_n) \end{pmatrix}$$

$n \times M$ matrix

$$\phi(x) = (\phi_1(x), \phi_2(x), \dots, \phi_M(x))^T$$

$$w = (w_1, w_2, \dots, w_M)^T$$

$$t = (t_1, t_2, \dots, t_n)^T$$

(Φ, t) are a sufficient statistic for the data (under this model)

$$\cdot \text{likelihood } p(D | w, \overset{\text{model}}{M}) \propto \exp\left(-\sum_{i=1}^n \frac{\beta}{2} (t_i - w^T \phi(x_i))^2\right)$$

(assuming β is known)

Frequentis regression

• maximize $L_D(w) \Leftrightarrow$ maximize $\ell(w) = \log L(w)$

$$\Leftrightarrow \text{minimize } \sum_{i=1}^n (t_i - w^T \phi(x_i))^2$$

ie - Least squares!

$$\bullet W_{MLE} = \underbrace{\bar{\Phi}^T}_{\text{Moore-Penrose pseudoinverse}} t = \underbrace{(\bar{\Phi}^T \bar{\Phi})^{-1} \bar{\Phi}^T}_{\text{MLE estimator for regression coeffs}} t$$

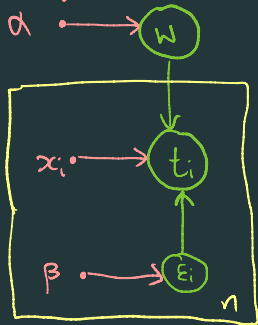
Bayesian linear regression

Model -
$$t_i = \sum_{j=1}^M w_j \phi_j(x_i) + \epsilon_i$$

• Now w_1, w_2, \dots, w_M are random (but common to all data)

$$\epsilon_i \sim \mathcal{N}(0, 1/\beta), \text{ iid}$$

prior hyperparameters



•
$$W = \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_M \end{pmatrix} \sim \mathcal{N}\left(0, T_0^{-1}\right)$$

↑
precision matrix
(i.e. $T_0 = \Sigma^{-2}$)

eg - $T_0 = \alpha^{-1} I$

$\Rightarrow \sigma^2 = 1/\alpha$, and $w_i \sim \mathcal{N}(0, \sigma^2)$, iid

Bayesian linear regression (generalizes the normal-normal model to M dimensions)

- data $D = \{(t_1, x_1), (t_2, x_2), \dots, (t_N, x_N)\} \in \mathbb{R}^n$
- model $\mathcal{M}: t_i = \sum_{j=0}^{M-1} W_j \phi(x_i) + \epsilon_i$, where $\epsilon_i \sim \mathcal{N}(0, \beta^{-1})$ ↖ known precision

Bayesian linear regression model - hyperparameters - $\beta, \alpha, (M, (\text{scale}, \text{loc}) \text{ for basis fns})$

- likelihood: $p(D|W) \propto \exp\left(-\beta \sum_{i=1}^N (x_i - W^T \phi(x_i))^2 / 2\right)$
- prior: $W \sim \mathcal{N}(0, \alpha^{-1} I)$, i.e., $W_j \sim \mathcal{N}(0, 1/\alpha)$ ↖ m_W
- posterior: let $m_D = \underbrace{T_D^{-1} \beta \Phi^T t}_{\text{pseudo inverse}}$ and $T_D = \underbrace{\beta \Phi^T \Phi}_{\text{data precision}} + \underbrace{\alpha I}_{\text{prior precision}}$
 $p(W|D) \sim \mathcal{N}(m_D, T_D^{-1})$

Recall - $W_{\text{MLE}} = (\Phi^T \Phi)^{-1} \Phi^T t$

$$m_D = \left(\Phi^T \Phi + \underbrace{\frac{\alpha}{\beta} I}_{\text{regularizer}} \right)^{-1} \Phi^T t$$

Note - even though W_i were indep in prior, they are dependent conditioned on data (explaining away...)

Bayesian linear regression

- data $D = \{(t_1, x_1), (t_2, x_2), \dots, (t_N, x_N)\} \in \mathbb{R}^n$
- model \mathcal{M} : $t_i = \sum_{j=0}^{M-1} W_j \phi(x_i) + \epsilon$, where $\epsilon \sim \mathcal{N}(0, \beta^{-1})$

Bayesian linear regression model

- likelihood: $p(D|W) \propto \exp\left(-\beta \sum_{i=1}^N (x_i - W^T \phi(x_i))^2 / 2\right)$
- prior: $W \sim \mathcal{N}(0, \alpha^{-1}I)$
- posterior: let $m_D = T_D^{-1} \beta \Phi^T t$ and $T_D = \beta \Phi^T \Phi + \alpha I$

$$p(W|D) \sim \mathcal{N}(m_D, T_D^{-1})$$

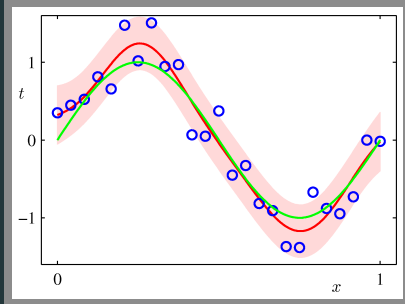
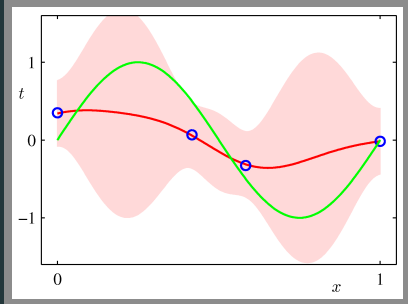
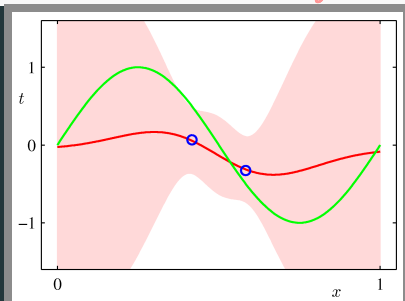
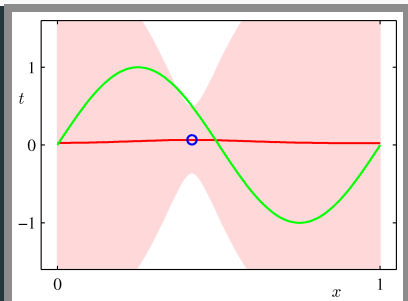
- posterior predictive distribution: i.e., what is $p(t|D)$ for new x

$$p(t|D) \sim \mathcal{N}(m_D^T \phi(x), \underbrace{\beta^{-1} + \phi(x)^T T_D^{-1} \phi(x)}_{\text{variances add up, depends on } x})$$

variances add up, depends on x

Bayesian linear regression: posterior prediction

Gaussian basis fns
true model $y(x) = \sin(2\pi x)$



Bayesian linear regression: posterior sampling

